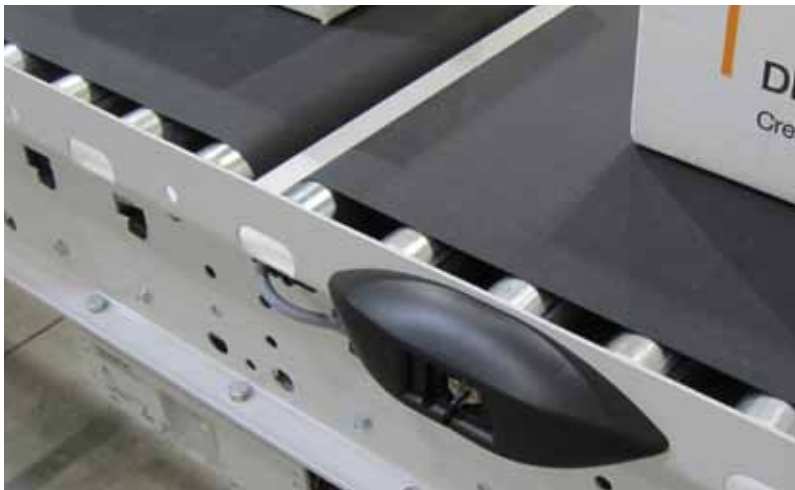


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conveyor and processing belts

ELASTIC BELTS

RECOMMENDATIONS FOR MACHINE DESIGN



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RECOMMENDATIONS FOR MACHINE DESIGN

Calculating the shaft load

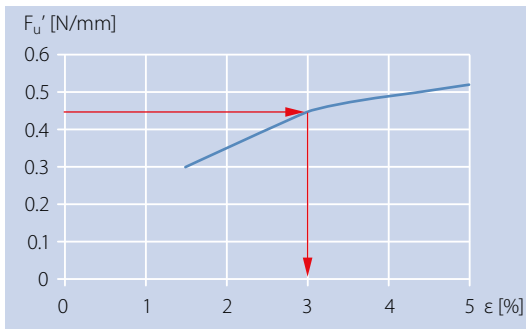


Diagram 1 – Specific effective pull F_u' [N/mm]

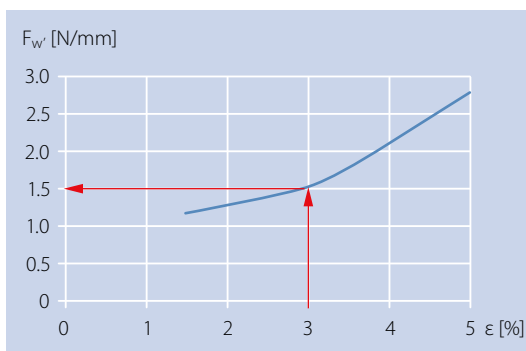


Diagram 2 – Specific shaft load F_w' [N/mm]

The ideal elongation range is between 1.5 and 5.0%.
We recommend our B_Rex calculation program for sizing belts.

A rough calculation can be made based on the following example:

Unit weight m	[kg]	35
Band width b	[mm]	400
Conveying speed	[m/s]	2
Acceleration a	[m/s ²]	2
Friction coefficient μ_{steel}		0.2 (for new belts)
Friction coefficient μ_{steel}		0.3 (on older friction surfaces)
Friction coefficient μ_{Roll}		0.03 (with rolling support)
Friction coefficient $\mu_{\text{galvanized steel}}$		0.4 (with galvanized support)

$$F_u = m \cdot g \cdot \mu + m \cdot a + \text{number of returns} \times 20 \text{ N}$$

$$= 35 \text{ kg} \cdot 9.81 \text{ kg} \cdot \text{m/s}^2 \times 0.2 + 35 \text{ kg} \cdot 2 \text{ m/s}^2 + 2 \cdot 20 \text{ N} = 179 \text{ N}$$

$$F_u' = F_u / b = 179 \text{ N} / 400 \text{ mm} = 0.45 \text{ N/mm}$$

- > Refer to diagram 1 for the elongation required (in this example $\epsilon = 3\%$)
- > Refer to diagram 2 for the resulting shaft load (in this example $F_w' = 1.5 \text{ N/mm}$)

$$F_w = F_w' \times b = 1.5 \text{ N/mm} \times 400 \text{ mm} = \mathbf{600 \text{ N}}$$

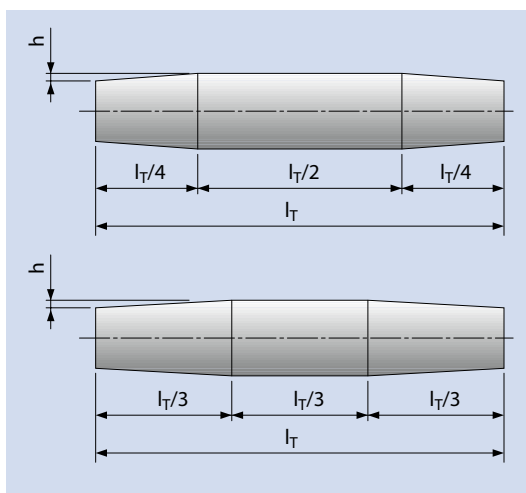
Length tolerances

Belts without tracking profile: $+0/-1.0$ [% belt length]

Belts with tracking profile: $+0/-1.5$ [% belt length]

Take this information into account when placing an order. An appropriate take-up range must be provided for when designing the conveyor.

Design information for belts without tracking profile



Drum design

At least one drum must be conical-cylindrical in order to control the belt.

Conicity height h depends on the drum length l_T :

l_T [mm]	< 200	400–600	600–1000	> 1000
h [mm]	0.4	0.6	1.0	1.2

Reversing operation

For reversing operation, at least 10 mm play should be allowed for between the edge of the belt and edge of the slider bed.

Recommended design of conical-cylindrical drums

Drive types

The following types of drums should be used depending on the drive:



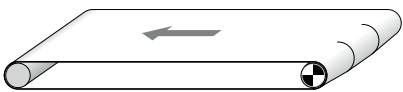
Head drive

Drive drum:

conical-cylindrical

End drum:

cylindrical



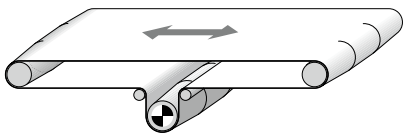
Tail drive:

Drive drum:

conical-cylindrical

End drum:

cylindrical (optionally: conical-cylindrical)



Center drive and reversing operation

Drive drum:

conical-cylindrical

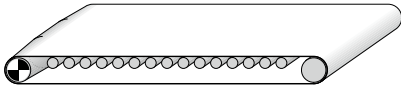
End drum:

conical-cylindrical

Snub roller:

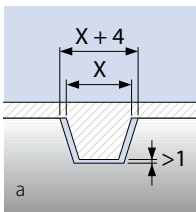
cylindrical

Rolling support



Rolling support instead of a sliderbed could also be provided and also reduces the effective pull.

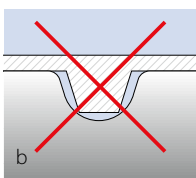
Design information for belts with tracking profile



Despite the fact that the EL types are very easy to fit, tracking profiles must be applied when using cylindrical rollers.

The following points need to be observed in the process:

- All drums must be cylindrical
- At least one drum has to be adjustable in order to fit the belt
- The drum groove should be a wedge shape as in “a” (parallel to the profile form) and not rounded as in “b”
- The slider bed groove should be designed to comply with “a” and be at least as wide as the drum groove (in the case of very short and wide belts with profiles we advise belt guidance via the drum and not the slider bed – in contrast to the recommendation for long belts).



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Forbo Siegling GmbH

Lilienthalstrasse 6/8, D-30179 Hannover
Phone +49 511 6704 0
www.forbo-siegling.com, siegling@forbo.com



MOVEMENT SYSTEMS